

## Lyapunov-type inequality of a second-order system of dynamic equations on time scales

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**Abstract** In this note, we establish a Lyapunov-type inequality for the following second-order system of dynamic equations

$$(A(t)x^\Delta(t))^\Delta + B(t)x^\sigma(t) = 0$$

on the time scale interval  $[a, b]_{\mathbf{T}} \equiv [a, b] \cap \mathbf{T}$  for some  $a, b \in \mathbf{T}$ , where  $A(t), B(t)$  are real  $n \times n$  symmetric matrix-valued functions on  $[a, b]_{\mathbf{T}}$  and  $x$  is a real vector-valued function on  $[a, b]_{\mathbf{T}}$ .

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## 1 Introduction

In 1990, Hilger introduced in [7] the theory of time scales with one goal being the unified treatment of differential equations (the continuous case) and difference equations (the discrete case). A time scale  $\mathbf{T}$  is an arbitrary nonempty closed subset of the real numbers  $\mathbf{R}$ , which has the topology that it inherits from the standard topology on  $\mathbf{R}$ . The two most popular examples are  $\mathbf{R}$  and the integers  $\mathbf{Z}$ . For the time scale calculus and some related basic concepts, we refer the readers to the books by Bohner and Peterson [2,3] for further details.

In this note, we study Lyapunov-type inequality for the following second-order system of dynamic equations

$$(A(t)x^\Delta(t))^\Delta + B(t)x^\sigma(t) = 0 \tag{1.1}$$

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on the time scale interval  $[a, b]_{\mathbf{T}} \equiv [a, b] \cap \mathbf{T}$  for some  $a, b \in \mathbf{T}$ , where  $A(t), B(t)$  are real  $n \times n$  symmetric matrix-valued functions on  $[a, b]_{\mathbf{T}}$  and  $x$  is a real vector-valued function on  $[a, b]_{\mathbf{T}}$ .

When  $n = 1$ ,  $A(t) = 1$  and  $\mathbf{T} = \mathbf{R}$ , (1.1) reduces to

$$x''(t) + B(t)x(t) = 0. \tag{1.2}$$

In 1907, Lyapunov [10] showed that if  $B \in C([a, b], \mathbf{R})$  and  $x(t) \neq 0$  ( $t \in [a, b]$ ) is a solution of (1.2) with  $x(a) = x(b) = 0$ , then the following classical Lyapunov inequality holds:

$$\int_a^b |B(t)| dt > \frac{4}{b-a}.$$

Moreover, the above inequality is optimal.

When  $n = 1$ ,  $A(t) = 1$  and  $\mathbf{T} = \mathbf{Z}$ , (1.1) reduces to

$$\Delta^2 x(m) + B(m)x(m+1) = 0. \tag{1.3}$$

In 1983, Cheng [5] investigated (1.3) under the assumptions  $x(a) = x(b) = 0$  and  $x(m) \neq 0$  for  $m \in \{a, a+1, \dots, b\}$  and obtained the following Lyapunov inequality

$$\sum_{n=a}^{b-2} B(m) \geq \begin{cases} \frac{4(b-a)}{(b-a)^2-1}, & \text{if } b-a-1 \text{ is even,} \\ \frac{4}{b-a}, & \text{if } b-a-1 \text{ is odd.} \end{cases}$$

When  $n = 1$  and  $A(t) = 1$ , (1.1) reduces to

$$x^{\Delta^2}(t) + B(t)x^{\sigma}(t) = 0. \tag{1.4}$$

In 2002, Bohner et al. [1] investigated (1.4) under the assumptions  $x(a) = x(b) = 0$  and  $x(t) \neq 0$  for  $t \in [a, b]_{\mathbf{T}}$  and  $B : [a, b]_{\mathbf{T}} \rightarrow (0, \infty)$  is rd-continuous, and obtained the following Lyapunov inequality

$$\int_a^b B(t) \Delta t \geq \frac{b-a}{C},$$

where  $C = \max\{(t-a)(b-t) : t \in [a, b]_{\mathbf{T}}\}$ .

In 2006, Wong et al. [12] investigated the following dynamic equation

$$(A(t)x^{\Delta}(t))^{\Delta} + B(t)x^{\sigma}(t) = 0 \tag{1.5}$$

under the assumptions  $x(a) = x(b) = 0$  and  $A \in C_{rd}([a, b]_{\mathbf{T}}, (0, \infty))$  is monotone and  $B \in C_{rd}([a, b]_{\mathbf{T}}, \mathbf{R})$ , and showed that if  $x(t) \neq 0$  for  $t \in [a, b]_{\mathbf{T}}$  is a solution of (1.5), then

$$\int_a^b \max\{B(t), 0\} \Delta t \geq \begin{cases} \frac{A(a)(b-a)}{A(b)C}, & \text{if } A \text{ is increasing,} \\ \frac{A(b)(b-a)}{A(a)C}, & \text{if } A \text{ is decreasing,} \end{cases}$$

where  $C = \max\{(t - a)(b - t) : t \in [a, b]_{\mathbf{T}}\}$ .

For some other related results on Lyapunov inequality, see, for example, [4,6,8, 11].

## 2 Main Result and its Proof

For any  $x \in \mathbf{R}^n$  and any  $A \in \mathbf{R}^{n \times n}$  (the space of real  $n \times n$  matrices), denote by

$$|x| = \sqrt{x^T x} \quad \text{and} \quad |A| = \sup_{x \neq 0} \frac{|Ax|}{|x|}$$

the Euclidean norm of  $x$  and the matrix norm of  $A$  respectively, where  $C^T$  is transpose of a  $n \times m$  matrix  $C$ . It is easy to show

$$|Ax| \leq |A||x|$$

for any  $x \in \mathbf{R}^n$  and any  $A \in \mathbf{R}^{n \times n}$ . Let  $A \in \mathbf{R}^{n \times n}$  is a symmetric matrix, we say that  $A$  is semi-positive definite (resp. positive definite), written as  $A \geq 0$  (resp.  $A > 0$ ), if  $x^T Ax \geq 0$  (resp.  $x^T Ax > 0$ ) for all  $x \in \mathbf{R}^n$ . If  $A$  is semi-positive definite (resp. positive definite), then there exists a unique semi-positive definite matrix (resp. positive definite matrix), written as  $\sqrt{A}$ , such that  $[\sqrt{A}]^2 = A$ .

**Lemma 1** Let  $A(t) > 0$  be an integrable real  $n \times n$  matrix-valued function,  $u, v \in [a, b]_{\mathbf{T}}$  and  $x$  be an integrable real vector-valued function. Then

$$\int_v^u |\sqrt{A(t)}x^\Delta(t)|^2 \Delta t \geq \frac{|x(u) - x(v)|^2}{\int_v^u |[\sqrt{A(t)}]^{-1}|^2 \Delta t},$$

where  $C^{-1}$  denote the inverse matrix of  $C$ .

**Proof** Write  $W = \frac{x(u) - x(v)}{\int_v^u |[\sqrt{A(t)}]^{-1}|^2 \Delta t}$ . Then

$$\int_v^u |\sqrt{A(t)}x^\Delta(t) - [\sqrt{A(t)}]^{-1}W|^2 \Delta t \geq 0,$$

which implies

$$\begin{aligned} & \int_v^u (\sqrt{A(t)}x^\Delta(t) - [\sqrt{A(t)}]^{-1}W)^T (\sqrt{A(t)}x^\Delta(t) - [\sqrt{A(t)}]^{-1}W) \Delta t \\ = & \int_v^u |\sqrt{A(t)}x^\Delta(t)|^2 \Delta t - \int_v^u W^T \{[\sqrt{A(t)}]^{-1}\}^{-1} \sqrt{A(t)}x^\Delta(t) \Delta t \\ & - \int_v^u [x^\Delta(t)]^T [\sqrt{A(t)}]^{-1} W \Delta t + \int_v^u |[\sqrt{A(t)}]^{-1}W|^2 \Delta t \\ = & \int_v^u |\sqrt{A(t)}x^\Delta(t)|^2 \Delta t - 2 \int_v^u W^T x^\Delta(t) \Delta t + \int_v^u |[\sqrt{A(t)}]^{-1}W|^2 \Delta t \\ \geq & 0. \end{aligned}$$

That is

$$\begin{aligned}
 \int_v^u |\sqrt{A(t)}x^\Delta(t)|^2 \Delta t &\geq 2 \int_v^u W^T x^\Delta(t) \Delta t - \int_v^u |[\sqrt{A(t)}]^{-1}W|^2 \Delta t \\
 &\geq 2 \int_v^u W^T x^\Delta(t) \Delta t - \int_v^u |[\sqrt{A(t)}]^{-1}|^2 |W|^2 \Delta t \\
 &= 2W^T(x(u) - x(v)) - W^T W \int_v^u |[\sqrt{A(t)}]^{-1}|^2 \Delta t \\
 &= \frac{|x(u) - x(v)|^2}{\int_v^u |[\sqrt{A(t)}]^{-1}|^2 \Delta t}.
 \end{aligned}$$

This completes the proof of Lemma 1.

We now can state and prove our main result.

**Theorem 1** If (1.1) has a solution  $x(t)$  satisfying  $x(a) = x(b) = 0$  and  $x(t) \neq 0$  for  $t \in [a, b]_{\mathbf{T}}$ , then

$$\int_a^b |\sqrt{B(t)}|^2 \Delta t \geq \frac{\int_a^b |[\sqrt{A(t)}]^{-1}|^2 \Delta t}{f(d)},$$

where  $f(d) = \max\{\int_a^t |[\sqrt{A(\tau)}]^{-1}|^2 \Delta \tau \int_t^b |[\sqrt{A(\tau)}]^{-1}|^2 \Delta \tau : t \in [a, b]_{\mathbf{T}}\}$ .

**Proof** Since  $|x(t)|^2$  is continuous in  $[a, b]_{\mathbf{T}}$ , we see that there exists an  $c \in (a, b)_{\mathbf{T}}$  such that

$$|x(c)|^2 = \max\{|x(t)|^2 : t \in [a, b]_{\mathbf{T}}\} > 0.$$

Then we have

$$\begin{aligned}
 M \int_a^b |\sqrt{B(t)}|^2 \Delta t &= \int_a^b |\sqrt{B(t)}|^2 M \Delta t \geq \int_a^b |\sqrt{B(t)}|^2 |x^\sigma(t)|^2 \Delta t \\
 &\geq \int_a^b |\sqrt{B(t)}x^\sigma(t)|^2 \Delta t = \int_a^b (\sqrt{B(t)}x^\sigma(t))^T \sqrt{B(t)}x^\sigma(t) \Delta t \\
 &= \int_a^b (x^\sigma(t))^T [\sqrt{B(t)}]^T \sqrt{B(t)}x^\sigma(t) \Delta t = \int_a^b (x^\sigma(t))^T B(t)x^\sigma(t) \Delta t \\
 &= - \int_a^b (x^\sigma(t))^T (A(t)x^\Delta(t))^\Delta \Delta t \\
 &= - \int_a^b ((x(t))^T A(t)x^\Delta(t))^\Delta \Delta t + \int_a^b ((x(t))^T)^\Delta A(t)x^\Delta(t) \Delta t \\
 &= \int_a^b ((x(t))^T)^\Delta A(t)x^\Delta(t) \Delta t = \int_a^b |\sqrt{A(t)}x^\Delta(t)|^2 \Delta t \\
 &= \int_a^c |\sqrt{A(t)}x^\Delta(t)|^2 \Delta t + \int_c^b |\sqrt{A(t)}x^\Delta(t)|^2 \Delta t \\
 &\geq \frac{|x(c) - x(a)|^2}{\int_a^c |[\sqrt{A(t)}]^{-1}|^2 \Delta t} + \frac{|x(b) - x(c)|^2}{\int_c^b |[\sqrt{A(t)}]^{-1}|^2 \Delta t} \quad (\text{by Lemma 1}) \\
 &= M \frac{\int_a^b |[\sqrt{A(t)}]^{-1}|^2 \Delta t}{\int_a^c |[\sqrt{A(t)}]^{-1}|^2 \Delta t \int_c^b |[\sqrt{A(t)}]^{-1}|^2 \Delta t}
 \end{aligned}$$

$$\geq M \frac{\int_a^b |[\sqrt{A(t)}]^{-1}|^2 \Delta t}{f(d)}.$$

That is

$$\int_a^b |\sqrt{B(t)}|^2 \Delta t \geq \frac{\int_a^b |[\sqrt{A(t)}]^{-1}|^2 \Delta t}{f(d)}.$$

This completes the proof of Theorem 1.

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